A Nonextremal Camion Basis

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ABSTRACT

We construct a 3×21 matrix A and Camion basis B of A such that B does not correspond to an extreme point of the convex hull of basic solutions of Ax = b for any $b \in \mathbb{R}^3$. Computer algebra methods played a critical role in finding both the matrix A and an analytic proof that B is not extremal.

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OVERVIEW

A column basis B of a rank m matrix $A \in \mathbb{R}^{m \times n}$ is a $Camion\ basis$ if there are nonsingular diagonal matrices D_m and D_n such that $D_m B^{-1}AD_n$ is nonnegative. Camion bases have many geometric and combinatorial interpretations: they correspond to simplicial regions of hyperplane arrangements $[6;\ 2,\ \$4.4]$ and mutations of realizable oriented matroids [5], and arise from depth-first-search trees of graphs (see [4]). Camion [3] first showed that every real matrix has at least one Camion basis. Shannon [6] proved that every matrix $A \in \mathbb{R}^{m \times n}$ of rank m has at least n Camion bases, and every column of A is contained in at least m of these bases. The notion of Camion bases has been generalized to oriented matroids, and the existence of Camion bases is a central open problem in oriented matroid theory $[2,\ \$7.3]$.

An interesting construction for Camion bases involves the basic solutions of the linear system Ax = b, where $b \in \mathbb{R}^m$ is in general position with respect to the columns of A. Given any column basis B, we write $x(B,b) \in \mathbb{R}^n$ for the corresponding basic solution. Let C(A,b) denote the convex hull in \mathbb{R}^n of the set of all basic solutions of Ax = b. Bland and Cho [1] showed that every vertex of C(A,b) gives rise to a Camion basis of A.

PROPOSITION 1 [1]. If a basic solution x = x(B, b) of Ax = b is a vertex of the convex polytope C(A, b), then the corresponding basis B is a Camion basis of A.

This raises the natural question whether each Camion basis of a real matrix can be obtained in this way. The answer is affirmative in the special cases $m \le 2$ and $n - m \le 2$ [4, §5.2]. It is the objective of this note to show that the answer is negative in general.

THEOREM 2. There exists a matrix $\tilde{A} \in \mathbb{R}^{3 \times 21}$ of rank three and a Camion basis B of \tilde{A} such that, for all $b \in \mathbb{R}^3$ in general position with respect to the columns of \tilde{A} , the basic solution x(B,b) is not a vertex of $C(\tilde{A},b)$.

The proof of Proposition 1 given in [1] is based on the following lemma, which is also used in our proof of Theorem 2. Two vectors x and y being consistent means that there are no coordinates i and j with $x_iy_i < 0 < x_jy_j$.

LEMMA 3 [1]. If x(B,b) is a vertex of C(A,b), then every column in B^{-1} A is consistent with $B^{-1}b$.

To derive Proposition 1 from Lemma 3, we first choose a nonsingular diagonal matrix D_m such that $D_m B^{-1} b$ is nonnegative. By consistency, each

column of $D_m B^{-1}A$ is either nonnegative or nonpositive, and we can choose a nonsingular diagonal matrix D_n such that $D_m B^{-1}AD_n$ is nonnegative.

Fix m = 3. A matrix $A \in \mathbb{R}^{3 \times n}$ is in *standard form* if A = [I, N], where I is the 3×3 identity matrix. We assume that the matrix $N \in \mathbb{R}^{3 \times (n-3)}$ is nonnegative, which implies that I is a Camion basis of A. Let W(A) denote the set of all vectors $b \in \mathbb{R}^3$ for which x(I, b) = (b, 0) is a vertex of C(A, b). This is a *semialgebraic set* (i.e., it is defined by polynomial inequalities), whose structure seems rather complicated in general.

Our method for finding and verifying the example of Theorem 2 was facilitated by numeric and symbolic computation. To gain insight into the problem, we generated random nonnegative matrices of rank three of the form [I, N]. Random vectors b were tested for extremality of x(I, b) using MATLAB, a package for matrix computations, and successes and failures were plotted. We found a 3×6 matrix A = [I, N] such that a large open region Δ of \mathbb{R}^3_+ appeared to contain no vector b for which the Camion basis I of A is extremal. Plots of the semialgebraic set W(A) were obtained using the computer algebra system MAPLE. The plots were consistent with the empirical observation that W(A) and Δ appear to be disjoint. This was verified analytically; W(A) excludes Δ . Replacing N in A by a row permutation N^* of N gives an excluded region Δ^* that is obtained from Δ by permuting the coordinates. The six Δ^* 's corresponding to all of the row permutations have as their union the entire nonnegative orthant. The 3×21 example of \bar{A} was produced by appending all six row permutations of N to I, resulting in exclusion of the entire nonnegative orthant, implying by Lemma 3, that I cannot be extremal for \tilde{A} . Details follow in the next section.

2. THE EXAMPLE

We consider the matrix A = [I, N], where

$$N = \begin{bmatrix} \frac{1}{1000} & \frac{3}{20} & \frac{1}{40} \\ \frac{9}{10} & \frac{4}{5} & \frac{1}{2} \\ \frac{2}{25} & \frac{1}{100} & \frac{1}{2} \end{bmatrix}.$$

Let Π_1,Π_2,\ldots,Π_6 be all six 3×3 permutation matrices. We claim that the 3×21 matrix

$$\tilde{A} = [I, \Pi_1 N, \Pi_2 N, \Pi_3 N, \Pi_4 N, \Pi_5 N, \Pi_6 N]$$

satisfies $W(\tilde{A}) = \emptyset$. In order to prove this claim (and hence Theorem 2), we observe

$$W(\tilde{A}) \subseteq W(\Pi_1 A) \cap W(\Pi_2 A) \cap W(\Pi_3 A)$$

$$\cap W(\Pi_4 A) \cap W(\Pi_5 A) \cap W(\Pi_6 A)$$

$$= \Pi_1 W(A) \cap \Pi_2 W(A) \cap \Pi_3 W(A)$$

$$\cap \Pi_4 W(A) \cap \Pi_5 W(A) \cap \Pi_6 W(A), \qquad (*)$$

which is easily verified from the definition of the operator $W(\cdot)$. Let Δ denote the triangle in \mathbb{R}^3 with vertices $(\frac{1}{3}, \frac{1}{3}, \frac{1}{3})$, (1, 0, 0), and $(\frac{1}{2}, 0, \frac{1}{2})$.

Lemma 4. For the matrix A above, the set W(A) is disjoint from the triangle Δ .

Proof of Theorem 2 from Lemma 4. The set W(A) is invariant under scaling by positive real numbers, which means W(A) is disjoint from the triangular cone $\mathbb{R}_+\Delta$. By (*), the set $W(\tilde{A})$ is disjoint from $\bigcup_{i=1}^6\Pi_i(\mathbb{R}_+\Delta)$. However, this union equals the entire nonnegative cone \mathbb{R}_+^3 . Therefore, by Lemma 3, the set $W(\tilde{A})$ is empty, as desired.

It remains to prove Lemma 4. Denoting the columns of A by a_1,\ldots,a_6 , the Camion bases of A are $I=[a_1,a_2,a_3],\ B_1=[a_1,a_4,a_5],\ B_2=[a_1,a_4,a_6],\ B_3=[a_2,a_4,a_6],\ B_4=[a_3,a_5,a_6],\ B_5=[a_1,a_2,a_5],\ and\ B_6=[a_2,a_3,a_4].$ Let L(b) denote the 3×6 matrix consisting of the last three rows of the 6×6 matrix $[x(B_1,b),x(B_2,b),\ldots,x(B_6,b)].$ Each entry of L(b) is a linear function of $b=(b_1,b_2,b_3).$ The 3×3 minor of L(b) with column indices $\{i< j< k\}\subset\{1,\ldots,6\}$ is abbreviated $D_{ijk}(b).$ This is a homogeneous polynomial of degree three in $b=(b_1,b_2,b_3).$

Suppose the $b \in W(A)$. Then there exists a vector $f \in \mathbb{R}^6$ such that $f' \cdot x(I,b) > f' \cdot x(B_i,b)$ for $i=1,2,\ldots,6$. Since A is in standard form, we may suppose $f=(0,0,0,c_1,c_2,c_3)$. Then the vector $c=(c_1,c_2,c_3)$ satisfies $c \cdot L(b) < 0$. Therefore there can be no nonnegative vector in the null space of L(b), except the zero vector. Cramer's rule implies that among the four expressions $D_{123}(b)$, $-D_{124}(b)$, $D_{134}(b)$, and $-D_{234}(b)$ at least one is positive and at least one is negative. We claim that this is not possible for any point $b \in \Delta$.

In order to see this, we apply the coordinate projection $(u, v, w) \rightarrow (u, v)$, which takes the triangle Δ bijectively onto the triangle Δ' in the (u, v)

plane having the vertices $(\frac{1}{3}, \frac{1}{3})$, (1, 0), and $(\frac{1}{2}, 0)$. The four polynomials in question transform into

$$\begin{split} D_{123}(u,v) &= \tfrac{400}{1353} (45u + 49v - 45) (864u + 47v - 44) (u + v - 1), \\ -D_{124}(u,v) &= \tfrac{20}{4961} v (45u + 49v - 45) (-1360u + 519v - 220), \\ D_{134}(u,v) &= \tfrac{20}{363} (-1382400u^3 - 1308560u^2v + 1452800u^2 \\ &\qquad + 238779uv^2 - 143260uv - 70400u + 14619v^3 \\ &\qquad -28039v^2 + 13420v), \\ -D_{234}(u,v) &= \tfrac{500}{1353} (-20u + v) (864u + 47v - 44) (u + v - 1). \end{split}$$

It remains to verify that all four polynomials are nonnegative for all (u,v) in the triangle Δ' . Verification for three of the four is easy, since the polynomials are products of linear terms. Verification for the remaining polynomial, D_{134} , was carried out by trapping the three roots of the univariate cubic polynomials $D_{134}(u,\alpha)$ in intervals outside of the interior of Δ' for each fixed value of α between 0 and $\frac{1}{3}$. The endpoints of each of the families of intervals are parametrized by a pair of linear functions of α on which D_{134} has opposite signs over all choices of α between 0 and $\frac{1}{3}$. This completes the proof of Lemma 4 and of Theorem 2.

Additional details and plots of the curves $D_{ijk}(u, v) = 0$ can be found in [4].

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